

# Human Powered Vehicle Competition

Department of Mechanical and Aerospace Engineering at the University of California, Irvine

## MISSION:

Design, fabricate and assemble an electrically-assisted, recumbent trike with off the shelf parts that is compact, ergonomic, adjustable, strong, and durable to compete in the National ASME competition.

## HPVC TEAM:

<u>Advisor</u> Professor David Copp	<u>Chief Engineer</u> Angelo Ilagan
<u>Project Managers</u> Christian Mason & Sophia Shannon	<u>Dynamics Lead</u> Jeffrey Lasher
<u>Statics Lead</u> Gabriel Sackinger	<u>Electrical Lead</u> Aviraj Singh
<u>MAE 93 Team</u> Rogel Aguilar, Jason Dick, Naethan Fajarito, Albert Huang, Wilson Huang, Sunny Lin, Ethan Macias, Steven Mejorado, Ocean Mou, Henry Nguyen, Jacob Pham, Neal Purohit, Matthew Quach	

## BUDGET

<u>Dynamics</u>	<u>Electrical</u>	<u>Statics</u>
Drive Train   \$758.27	Battery   \$180	Tubing   \$1199
Steering   \$479.81	Motor   \$490	Harness   \$70
Braking   \$169.71	E-Stop   \$12.91	Mirrors   \$16
	E-Box & Contents   \$257	

**TOTAL COST: \$3,632.70**

## SPECIAL THANKS

Professor David Copp, we couldn't have done this without your guidance and support.  
Tyler Schuldt, Jake Chutney, and Patrick Jerome Smyth for invaluable advice as well as making manufacturing on-campus possible.  
President Ailsa Watt and Vice President Ryan Mawlawi of ASME@UCI for supporting the team every step of the way.



## KEY FEATURES

- Material: 4130 Chromoly Steel Tubing | RPB 1.25"-0.0625" | Front Frame, 1.5"-0.0625" | Factor of Safety: 1.5
- The rollover protection system can withstand a side load of 1330 N and a top load of 2670 N [see "Finite Element Analysis"].
- The top speed of our bike is 29.6 MPH @ 100 RPM, and the maximum braking force from 25 KPH is 744 N and the braking distance 3.66 m
- 48V Lithium battery, emergency stop, electric motor to assist pedaling.

**LATE AUGUST**  
eHPVC Rules  
2024 Rules

**FALL QT.**  
Design  
Definition

**WINTER QT.**  
Manufacturing &  
Testing

**LATE APRIL**  
West Coast  
Competition BSU

## DYNAMICS SUBTEAM

**Objective: Implement efficient drivetrain with robust braking and steering systems.**  
**Drive Train:** 8-speed cassette with a 500W electric, mid-drive motor  
**Braking System:** Two front hydraulic brake calipers with 160mm rotors  
**Steering:** 10-bar indirect steering linkage, Rollover threshold of 0.6 G's, wheelbase length of 52", track width of 31"

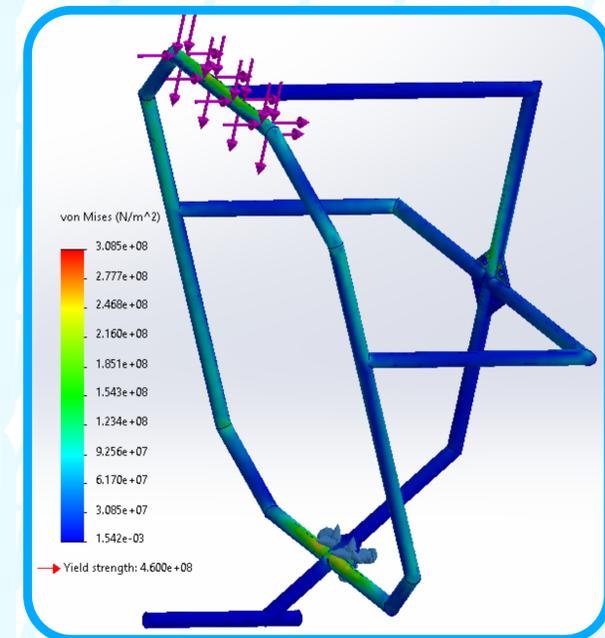
## ELECTRICAL SUBTEAM

**Objective: Safely provide power and data**  
**Electrical Box:** Polycarbonate weather-proof enclosure with a polyurethane gasket  
**Emergency Stop:** button to isolate the battery and motor in case of an emergency  
**Arduino:** microcontroller used to process IMU positioning data and display onto LCD screen

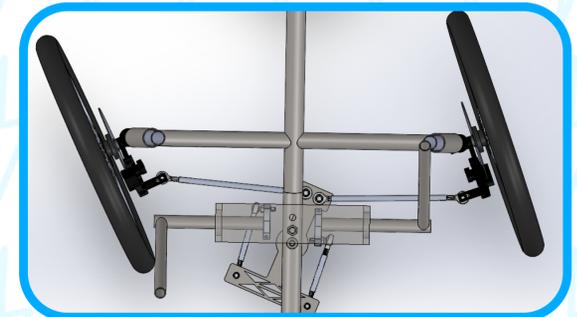
## STATICS SUBTEAM

**Objective: Keep the rider safe and comfortable.**  
**Rollover Protection Bar:** Protects passenger during loss of control  
**Carbon Fiber seat:** Set at 29 degrees from the horizontal for optimal comfort and is placed on an adjustable seat mount.  
**Custom Frame:** Split in two to make transportation easier and welded in house to reduce costs.

## FINITE ELEMENT ANALYSIS



## STEERING MECHANISM



Department of  
Mechanical and  
Aerospace Engineering

